

Robotics Master

Welcome to Robotics !

Download the
Presentation

QR



Prof. Francesco Mondada
Conseiller d'étude
Master Robotique



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Directeur de section
Microtechnique

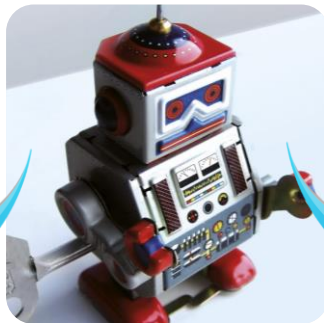
Robotics master



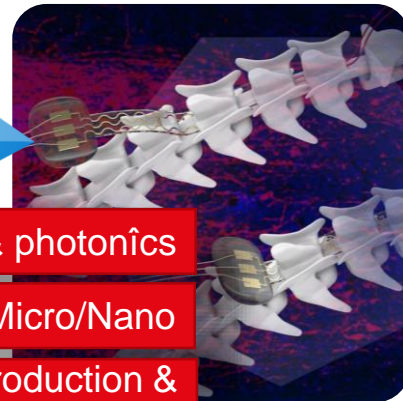
Industrial

Mobile

Medical



Microengineering master



Optics & photonics

Micro/Nano

Advanced production & manufacturing

Minors

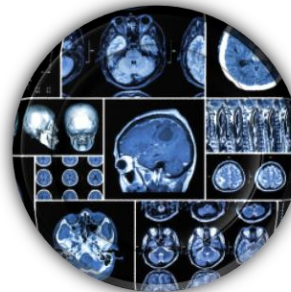
Optics & Photonics



Biomedical Technologies



Imaging



Other EPFL BaS programs

4.50 average

No mandatory prerequisite rules

Recommended background:

- Electronics
- Programming
- Mechanical design
- Microfab

Robotics master

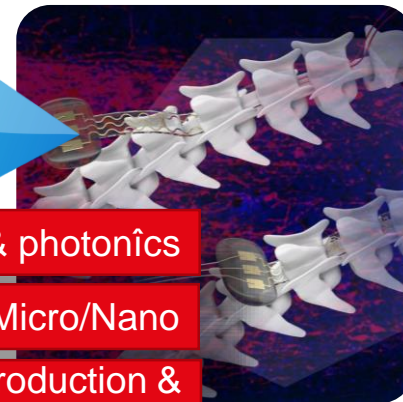


Industrial

Mobile

Medical

Microengineering master



Optics & photonics

Micro/Nano

Advanced production & manufacturing

Minors

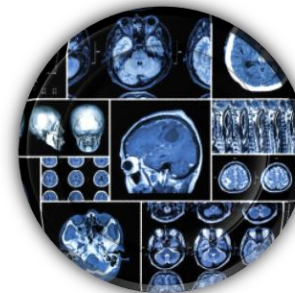
Optics & Photonics



Biomedical Technologies



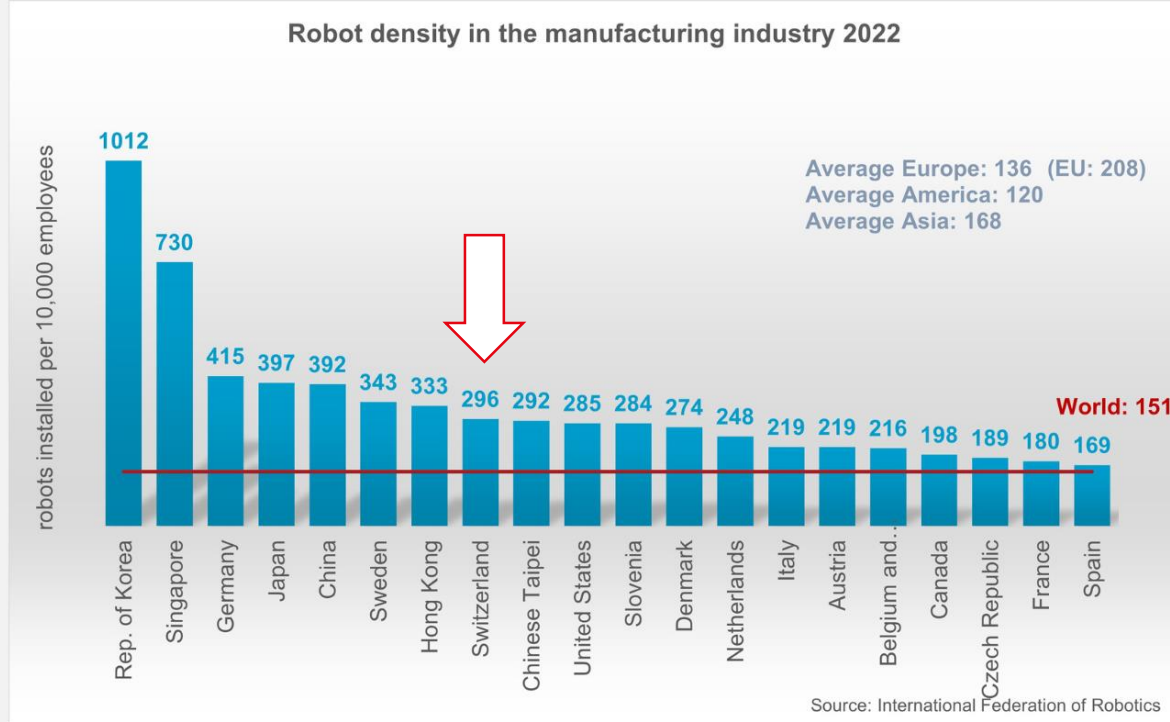
Imaging





Ce n'est pas un slogan marketing, c'est un fait: en robotique, la Suisse est championne du monde. «Si l'on prend le top 20 des labos dans le monde, pratiquement un quart sont en Suisse, alors que nous n'avons que huit millions d'habitants», confirme Aude Billard,

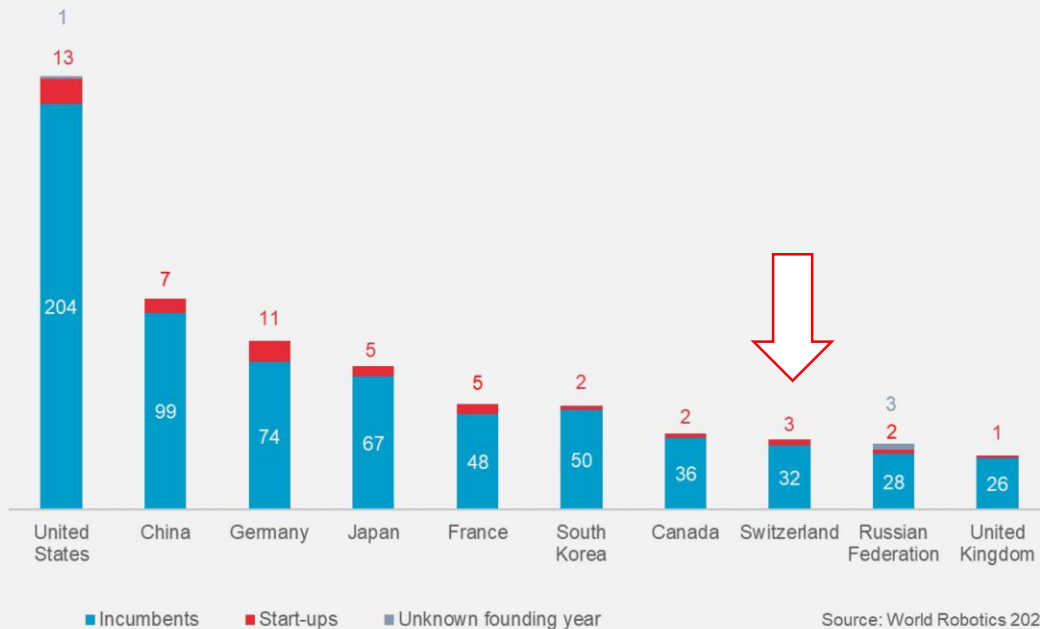
Switzerland in top 10 in automation



Top 10 in # of manufacturers of service robots

The United States is home of most service robot suppliers

Service robot manufacturers by country (top 10)
 all applications



Source: World Robotics 2023

28. Federal Institute of Technology Lausanne

 Switzerland | Lausanne

For Engineering

#4 in Europe

#1 in Switzerland

Enrollment 12,576



8. Federal Institute of Technology Lausanne

 Switzerland | Lausanne

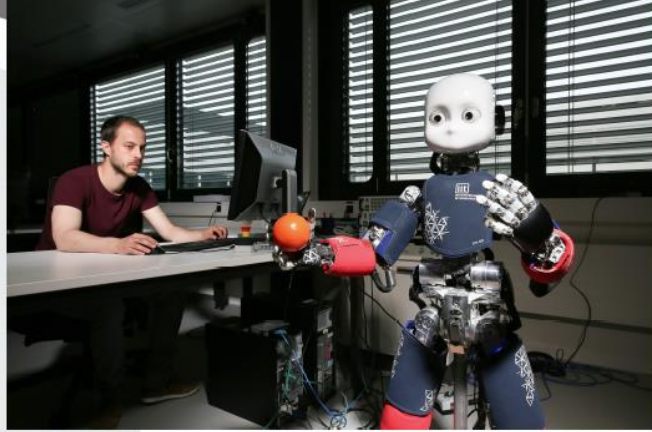
For Robotics

#1 in Europe

#1 in Switzerland



Robotics



Prof. Aude Billard



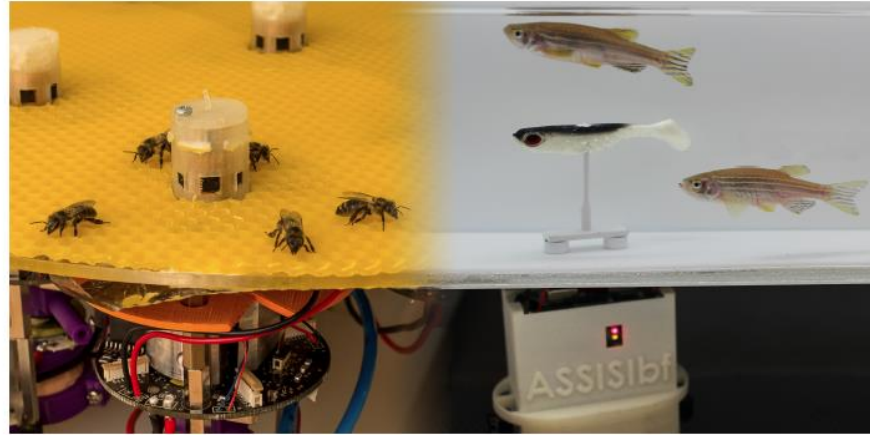
Prof. Dario Floreano



Prof. Auke Ijspeert



Prof. Silvestro Micera



Prof. Francesco Mondada

Diversité (écoles de provenance de nos candidats externes)

Technische Universität München	Allemagne
Technische Universität Wien	Autriche
Université Catholique de Louvain	Belgique
McGill University, Montreal	Canada
University of British Columbia, Vancouver	Canada
University of Toronto	Canada
University of Waterloo	Canada
Shanghai Jiao Tong University	Chine
The Hong Kong University of Science and Technology	Chine
Tsinghua University, Beijing	Chine
Universitat Politècnica de Catalunya, Barcelona	Espagne
Cornell University, Ithaca	Etats-Unis
Harvard University, Cambridge	Etats-Unis
University of California, Santa Barbara	Etats-Unis
University of Illinois at Urbana-Champaign	Etats-Unis
Ecole Polytechnique, Palaiseau	France
National Technical University of Athens	Grèce
Indian Institute of Technology Delhi	Inde
Indian Institute of Technology Kanpur	Inde
Indian Institute of Technology Madras	Inde
Politecnico di Milano	Italie
Politecnico di Torino	Italie
Università degli Studi di Roma "La Sapienza"	Italie
Delft University of Technology	Pays-Bas
Imperial College London	Royaume-Uni
University of Edinburgh	Royaume-Uni
Nanyang Technological University	Singapour
National University of Singapore	Singapour
Bogazici University, Istanbul	Turquie

Alumni careers

Careers after EPFL's MA Program in Robotics



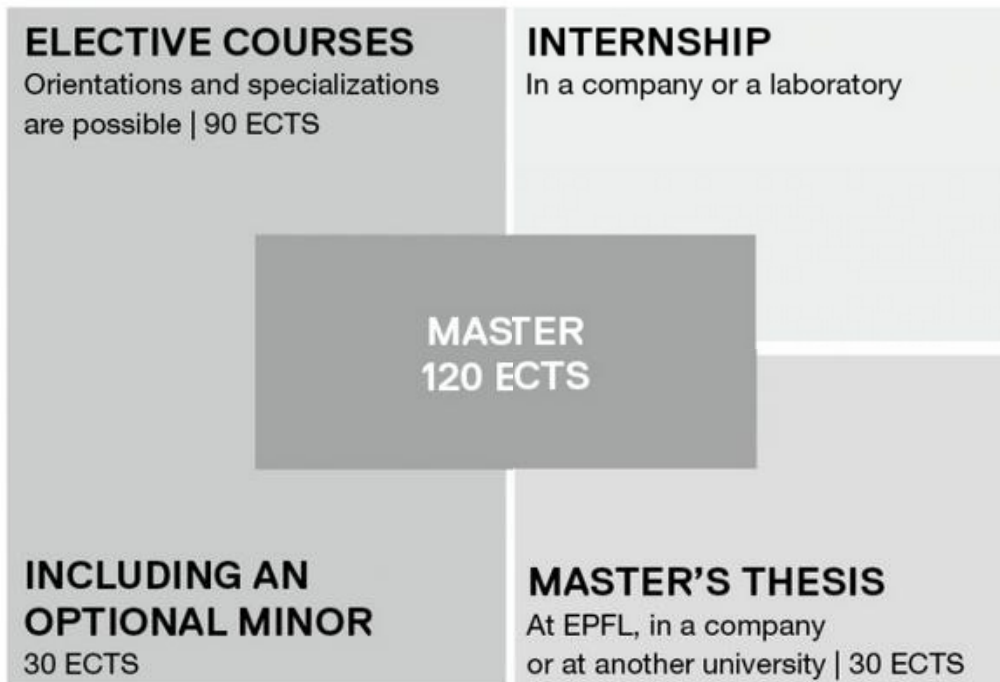
Quality

8. Please give your general appreciation and comments on the Robotics Master

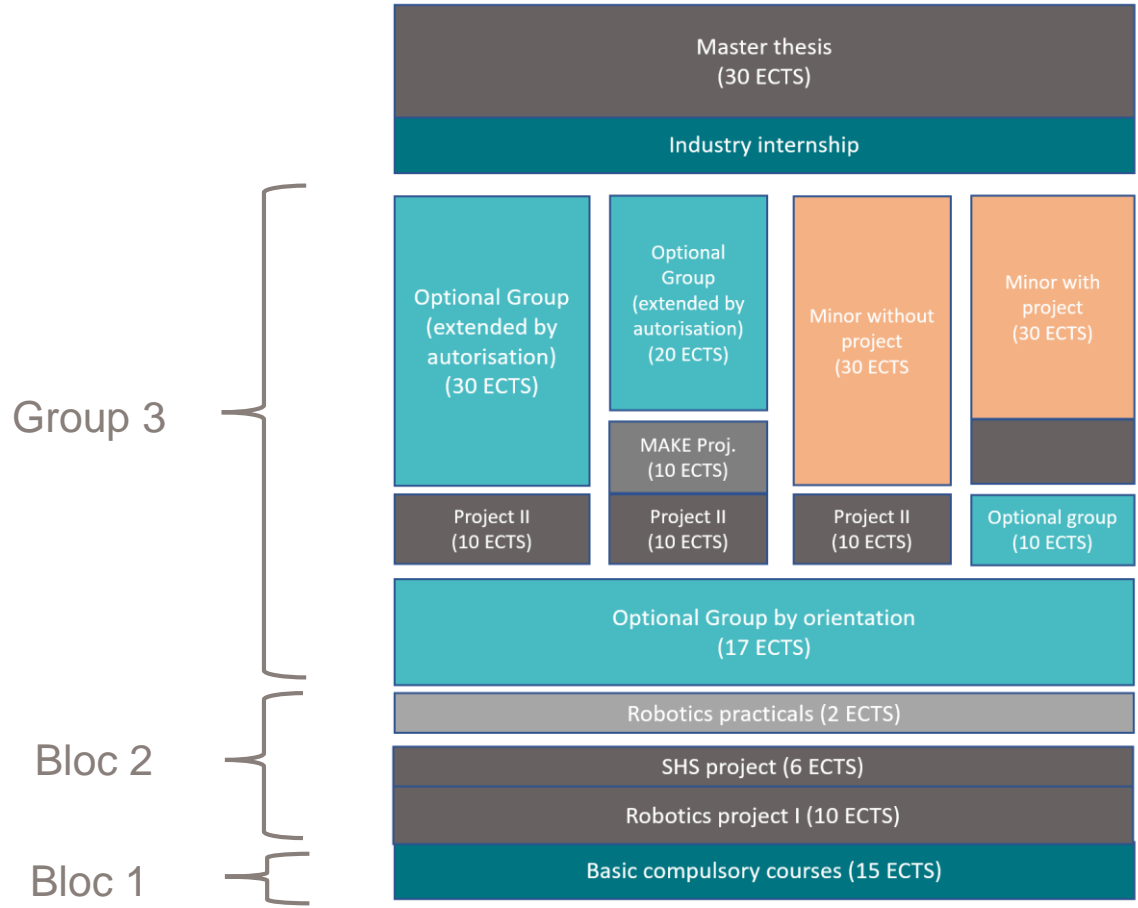
8.1) Overall, I find the Robotics Master of high quality



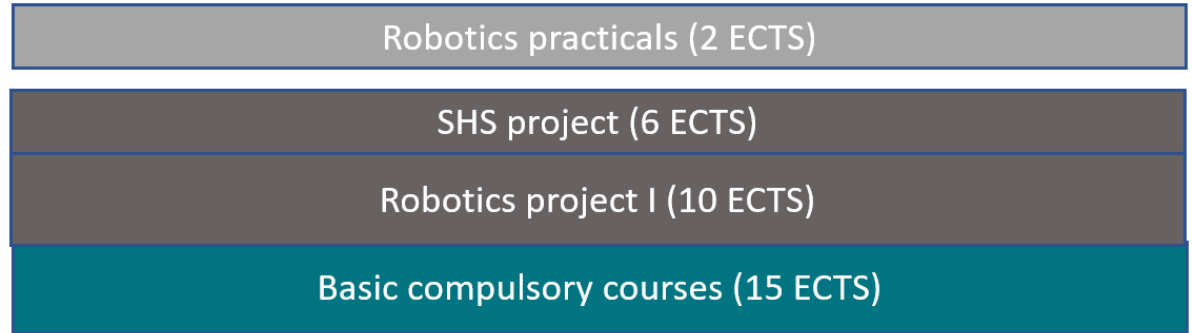
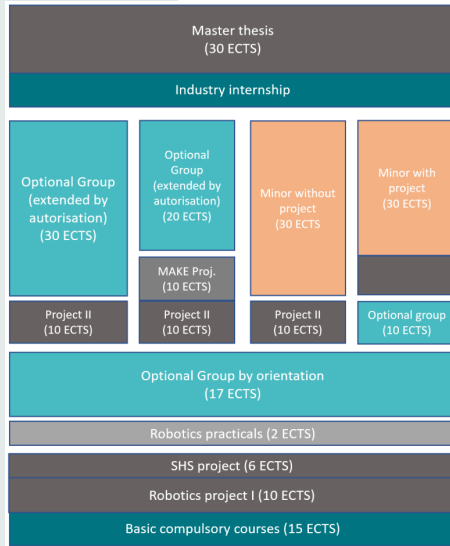
Master program structure



Master Program structure



Structure



Compulsory courses

Foundations :

- Basics of Mobile Robotics (4 ECTS; Mondada) – fall
- Basics of robotics for manipulation (3 ECTS; Bouri) – fall

Algorithms and Methods for Robotics :

- Machine learning I (4 ECTS; Billard) – fall
- Model Predictive Control (4 ECTS; Jones) – fall

Practicals:

- Robotics Practicals (2 ECTS; Mondada + all) - spring

Orientations

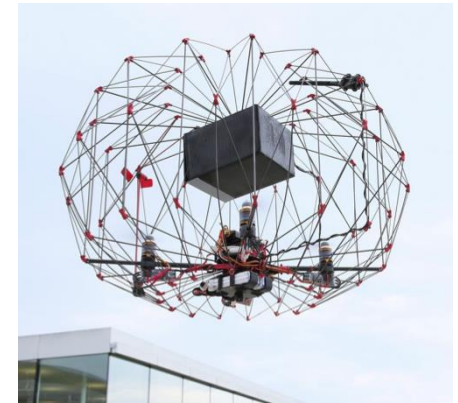
17 optional credits chosen among the optional courses of the chosen orientation, then free choice in robotics options.



Industrial Robotics



Medical Robotics

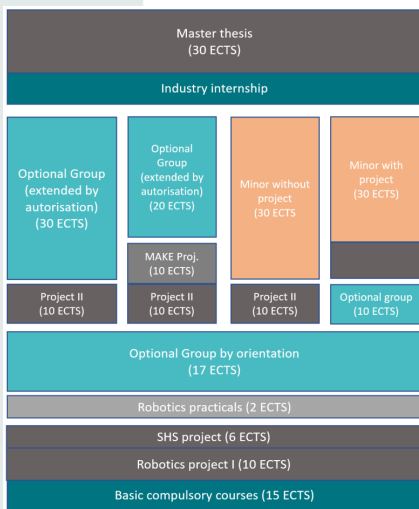


Mobile robotics

Orientations

Students must choose 17 ECTS of optional courses in one of these three orientations:

- A Industrial robotics
- B Medical robotics
- C Mobile robotics



Groupe à options
 Grand choix de cours
 (17 ECTS)

Optional courses and orientation	A	B	C	59
Advanced control systems	A	B	C	3
Advanced machine learning	A	B	C	4
Advanced MEMS & microsystems			C	3
Advanced satellite positioning			C	4
Analyse de produits et systèmes	A			2
Analysis and modeling of locomotion		B	C	4
Biomaterials		B		4
Commande embarquée de moteurs	A			2
Computational motor control		B	C	4
Computer vision	A	B	C	4
Conception mécanique intégrée	A			3
Continuous improvement of manufacturing systems	A			4
Controlling behavior in animal and robots		B	C	4
Deep learning	A	B	C	4
Distributed intelligent systems			C	5
Embedded systems	A	B	C	4
Evolutionary robotics			C	3
Flexible bioelectronics		B		4
Flying robots			C	4
Fundamentals of computer aided manufacturing	A			5
Fundamentals of neuroengineering			C	4
Haptic human robot interfaces	A			3
How technology shapes the workplace of the future	A	B	C	3
Image analysis and pattern recognition		B	C	4
Image processing I		B		3
Image processing II		B		3
Industrial automation	A			3
Industry dynamics, models & trends	A			4
Intelligent agents	A		C	6
Interdisciplinary project				10
				4
				3
				2
				5
				3
				4
				3
				3
				4
				2
				2
Production management	A			5
Real-time embedded systems	A	B	C	4
Robotique industrielle et appliquée	A			2
Sensorimotor neuroprosthetics		B		4
Sensor orientation			C	4
Sensors in medical instrumentation		B		3
Signal processing for functional brain imaging		B		3
System identification	A	B	C	3
Systèmes mécatroniques	A	B	C	5

Master in Robotics - Orientations

Options group : Fall

A: Industrial robotics

Commande embarqués moteurs

Intelligent agents

Production management

Image processing I

Applied data analysis
Commande non-linéaire
Systems programming for systems on a chip

B: Medical robotics

Basics of Bioinstrumentation

Neural interfaces

Neural signals and signal processing

Machine learning programming
Management de projet et analyse du risque
Mechanical product design and development

C: Mobile robotics

Multivariable control

Intelligent agents

Legged robots

Networked control systems

Principles of finance

17-47

Options group : Spring

Analyse de produits et systèmes

Applied and industrial robotics

Industrial automation

Optimal decision making

Haptic human robot interfaces

Image processing II

Continuous improvement of manufacturing systems

Numerical methods in biomechanics

Introduction to bioengineering

Sensors in medical instrumentation

Advanced mechanisms for extreme environments
Controlling behavior of animals and robots
Computational motor control

Deep learning for autonomous vehicles

Advanced MEMS and microsystems

Deep learning

Lifecycle performance of products systems

Sensor orientation

Advanced Satellite positioning

Learning and adaptive control for robots

Aerial robotics

Evolutionary robotics

Distributed intelligent systems

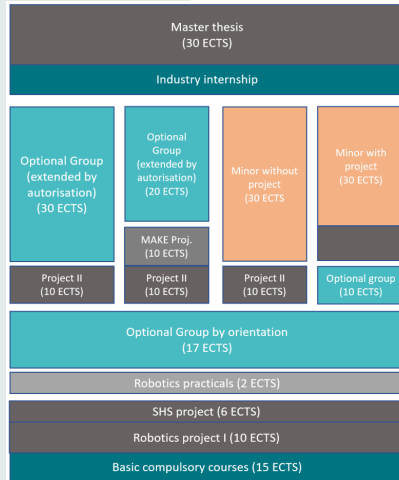
Image analysis and pattern recognition
Organic and printed electronics
Translational neuroengineering

Advanced control systems
Machine learning II
Computer vision
Convex optimization

Deep learning for optical imaging
Machine learning programming
Micro/nanorobotics
Embedded systems design

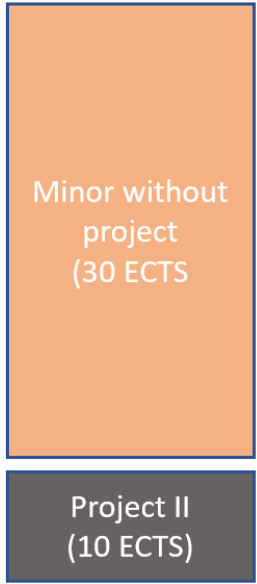
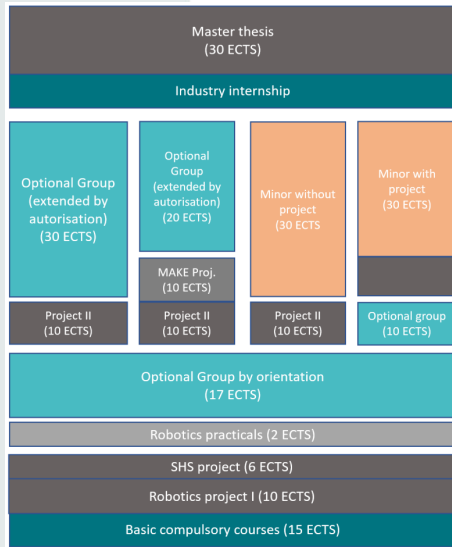
Reinforcement learning
Software architecture
Systèmes mécatroniques
System identification

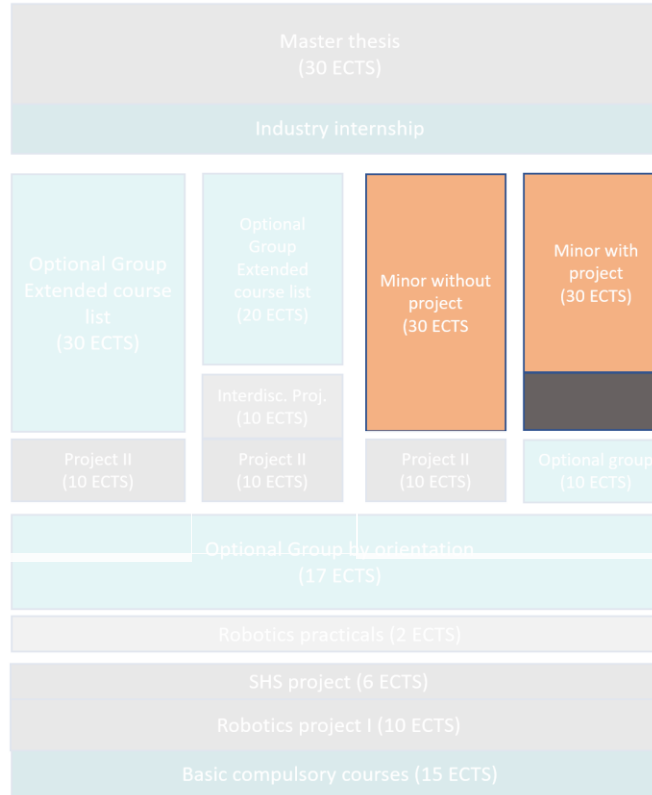
Orientation courses examples



2021-2022		ROBOTICS - Options	
Code	Matières	Enseignants	Crédits
MICRO-502	Aerial robotics	Floreano	3
MICRO-515	Evolutionary robotics	Floreano	3
MICRO-570	Advanced machine learning	Billard	4
EE-559	Deep learning	Fleuret	4
MICRO-514	Flexible bioelectronics	Lacour S.	4
EE-451	Image analysis and pattern recognition	Thiran J.-P.	4
MICRO-462	Learning and adaptative control for robots	Billard	4
MICRO-455	Applied machine learning	Billard	4
MICRO-553	Haptic human robot interfaces	Bouri	3
MICRO-401	Machine learning programming	Billard	2
BIOENG-404	Analysis and modelling of locomotion	Aminian/ljspeert/Courtine	4
BIOENG-456	Controlling behavior in animals and robots	Ramdya	4
CIVIL-459	Deep learning for autonomous vehicles	Alexandre Alahi	6
ENG-466	Distributed intelligent systems	Martinoli	5
CS-487	Industrial automation	Tournier/Sommer	3
MICRO-507	Legged robots	ljspeert	3
ENV-548	Sensor orientation	Skaloud	4

Free options





Recommended and possible Minors


Computer science	Discipl.	IN	Hazboun E.	r
Energy	Interdiscipl.	GM	Maréchal F.	r
Imaging	Interdiscipl.	MT	Sage Daniel	r
Engineering for sustainability	Interdiscipl.	SIE	Gilliéron P.Y. , Leterrier	r
Neuro-X	Discipl.	NX	Hummel F, Micera S.	r
Photonics	Interdiscipl.	MT	Martin O.	r
Physics of living systems	Interdiscipl.	SV	Persat A.	r
Quantum science and engineering	Discipl.	SIQ	Macris N. et Klinke H.	r
Biomedical technologies	Interdiscipl.	MT	Guiducci C.	r
Spacial technologies	Interdiscipl.	EL	Kneib J.-P.	r
Computational science and engineering	Discipl.	MA	Pouchon O.	c
Data and internet of things	Interdiscipl.	EL	Atienza D.	c
Technology management and entrepreneurship	Interdiscipl.	MTE	de Rassenfosse G.	c
Architecture	Discipl.	AR	Kochnitzky Palluel L.	c
Computational Biology	Interdiscipl.	IN	Salathé M.	c
Biotechnology	Interdiscipl.	CGC	Pick H.	c
Chemistry and chemical engineering	Discipl.	CGC	Marendaz J.-L.	c
Cyber security	Discipl.	IN	Hazboun E.	c
Data science	Discipl.	SC	Hazboun E.	c
Integrated Design, Architecture and Sustainability (IDEAS)	Interdiscipl.	AR	Andersen M., Rey E.	c
Territories in transformation and climate	Interdiscipl.	AR	Joost St.	c
Civil engineering	Discipl.	GC	Turberg P.	c
Electrical and electronic engineering	Discipl.	EL	Gay-Balmaz Ph.	c
Mechanical engineering	Discipl.	GM	Preneleoup A.	c
Systems Engineering	Interdiscipl.	MTE	Weber Th.	c
Life sciences engineering	Discipl.	SV	Grisoni B.	c
Financial engineering	Discipl.	IF	Fahlenbrach R.	c
Mathematics	Discipl.	MA	Pouchon O.	c
Physics	Discipl.	PH	Mari D.	c
Materials science and engineering	Discipl.	MX	Marselli B.	c
Environmental sciences and engineering	Discipl.	SIE	Gilliéron P.-Y	c
Statistics	Discipl.	MA	Mhalla L.	c
Communication systems	Discipl.	SC	Hazboun E.	c

r Recommended in the study plans
c Choice of the courses with the advice of the initiating section and the person in charge of the minor

Minors administrated by our section

mt EPFL
microtechnique
microengineering
section

Photonics minor 2023-24



Project obligatoire du mineur en Photonics

Project in photonics	Divers enseignants	10 AP
	Achuel/Martin O.	6 A

Bases en photonique pour étudiants n'ayant aucune formation en photonique
Ingenieur optique

Beneš-Chelms	4 A
Moser	3 P
Moser Ch./Kippenberg	4 A
Rohr	3 A
Gallinet	4 A
Pastus/Pu	3 P
Breit	4 P
Grissevain	4 P
Kippenberg	6 A
Brenard	6 P
Yatsev	6 A
Martin O.	3 A
Bulla	4 A
Beneš-Chelms	3 P

Foundations of photonics
Basic integrated photonic components: fundamentals and simulations
Laser fundamentals and applications for engineers
Lasers: theory and modern applications
Nonlinear optics
Nonlinear optical for quantum technologies
Optics laboratories
Photonics systems and technology
Physics of photonic microelectronic devices
Quantum electrodynamic and quantum optics
Quantum optical and quantum information
Quantum physics II
Spontaneous Brillouin scattering optics
Semiconductor physics and light-matter interaction
Advanced photonic transducers: classical and quantum applications

Applied photonics
Fundamentals & processes for photovoltaic devices
Fundamentals of biophotonics
Image processing I
Image processing II
Imaging optics
Laser microprocessing
Microfabrication technologies
Nanophotonics
Optical Design with ZEMAX OpticStudio
Optical Simulators
Organic and printed electronics

Baif	3 P
Rallavoin	3 P
Unser/Van de Ville	3 A
Leibling/Sage/Unser/Van de Ville	3 P
Pastus	3 P
Hofmann	2 P
Qui-Fingger	4 A
Mosconi	3 A
Pu	3 A
Beneš	3 A
Brenard/Sudramanian	2 P

Biomedical photonics
Biomedical optics
Biomicroscopy I
Biomicroscopy II
Photomedicine

Wagnières	3 A
Albug	3 A
Albug + Seitz A.	4 P
Wagnières	2 P

Discover the world of photonics!


Explore cutting-edge technologies to control electrons and photons

Contact : olivier.martin@epfl.ch

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mt EPFL
microtechnique
microengineering
section

Imaging minor 2023-24



Project obligatoire du mineur en Imagerie

Project in imaging	Divers enseignants	8 AP
	Unser/Simeoni/Guzdar	3 A

Bases en Imagerie

Mathematics of imaging (starting 24-25)

Unser/Simeoni/Guzdar	3 A
----------------------	-----

Autres cours

Instrumentation and Optics
Imaging optics
Metrology
Metrology practicals
Optical detectors
Electron microscopy: advanced methods
Fundamentals of biophotonics

Paalis	3 A
Charbon/Fandner/Bruschini	3 P
Charbon/Fandner/Bruschini	2 P
Besse	3 A
Hébert/Duncan	3 P
Radenovic	3 P

Image Processing and Analysis
Image analysis and pattern recognition
Image processing I
Deep learning for optical imaging
Lab in signal and image processing
Computational photography
Computer vision
Visual intelligence : machines and minds
Mathematical foundations of signal processing

Thiran	4 P
Unser/Van de Ville	3 A
Unser/Van de Ville/Leibling/Sage	3 P
Paalis	3 P
Thiran	4 P
Sustubnik	5 P
Fua	4 P
Zamer	5 P
Fageot/Simeoni/Bejar	6 A

Application-Specific Courses
Biomege informatics
Biomicroscopy I
Biomicroscopy II
Fundamentals of biomedical imaging
Neural signal and signal processing
Image processing for Earth observation
Qualitative imaging for civil engineering
Sensing and spatial modeling for earth observation
Histoire de l'image I

Seitz/Sage	4 P
Albug	3 A
Albug/Seitz	4 P
Grueter	4 P
Moceri/Van De Ville	6 A
Tula	4 A
Anis	3 A
Skaloud, Beme, Tula	5 P
Lugon	3 A

Unlock the power of imaging!

Dive into this fascinating field covering a large panel of engineering sciences

Contact : daniel.sage@epfl.ch & laurene.donati@epfl.ch

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microtechnique
microengineering
section

Biomedical technologies minor 2023-24



Project obligatoire du mineur en Technologies biomédicales

Project in biomedical technologies	Divers enseignants	8 AP
	Manley	3 P
	Zilberly	4 A
	Roy	4 P
	Radenovic	2 A

Bases biomédicales
Biophysics : physics of the cell
Cellular biology and biochemistry for engineers
Physiologie par systèmes
Seminar in physiology and instrumentation

Manley	3 P
Zilberly	4 A
Roy	4 P
Radenovic	2 A

Autres cours

Analog circuits for biochip
Applied biomedical signal processing
Bioelectronics and bio-medical microelectronics
Biomege informatics
Basics in Biomaterials +
Computational neurosciences : neuronal dynamics
Biomechanics of the cardiovascular system
Biomechanics of the musculoskeletal system
Biomedical optics
Biomicroscopy I
Biomicroscopy II
Bio-nano-chip design
Biophysics : physics of biological systems
Fundamentals of biomedical imaging
Fundamentals of biophotonics
Fundamentals of biosensors and electronic biochips
Ingenieur optique
Light, liquids and interfaces
Mechanobiology: how mechanics regulate life
Microfabrication technologies
Nanobiotechnology and biophysics
Neural interfaces
Neural signals and signal processing
Neuroscience: cellular and circuit mechanisms
New tools & research strategies in personalized health
Numerical methods in biomechanics
Sensors in medical instrumentation
Translational neuroengineering

Camara/Schmid/Skivervik	3 P
Leimay	4 A
Schweid	3 A
Sage/Seitz	4 P
Martin	4 A
Gestner	5 P
Siergopoulos	3 P
Planes	5 P
Wagnières G.	3 A
Albug	3 A
Albug/Seitz A.	4 P
Camara	3 A
Baib, Bahend J.	4 A
Grueter	4 P
Radenovic A.	4 A
C. Guiducci	3 A
Achour/Martin O.	6 A
Baib S.	4 A
Penas/Sakar	3 A
Bigger/Ges	4 A
Fries B.	3 P
Lacour	6 A
Moceri/Van De Ville	6 A
Crochet/Petersen	5 A
Tono	4 P
Teller A.	3 P
Crochet/Bonucci	3 P
Blawieck/Courth-Hummel/Moceri	6 P

Experience the future of biomedical technologies!

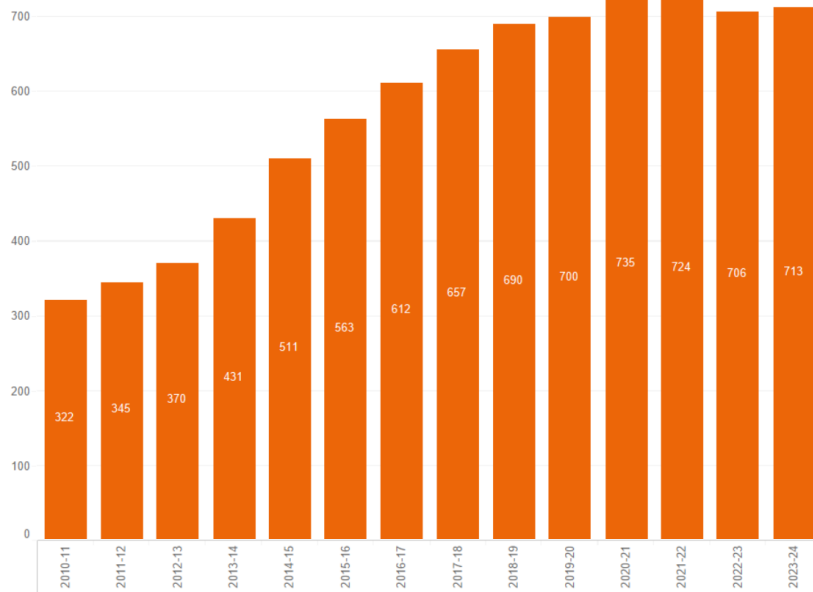
Join this program to transform the way we understand and treat the human body

Contact : carlotta.guiducci@epfl.ch

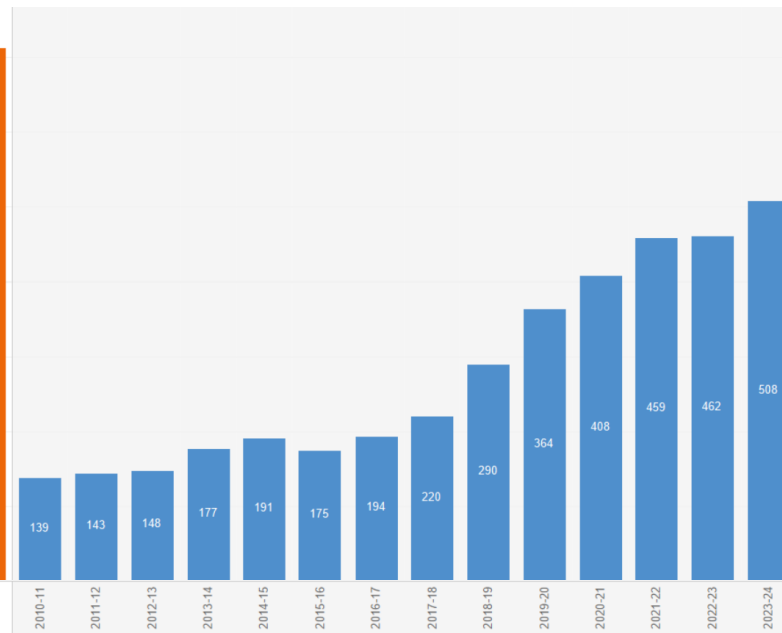
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Successful curricula (>1200 students)

Bachelor

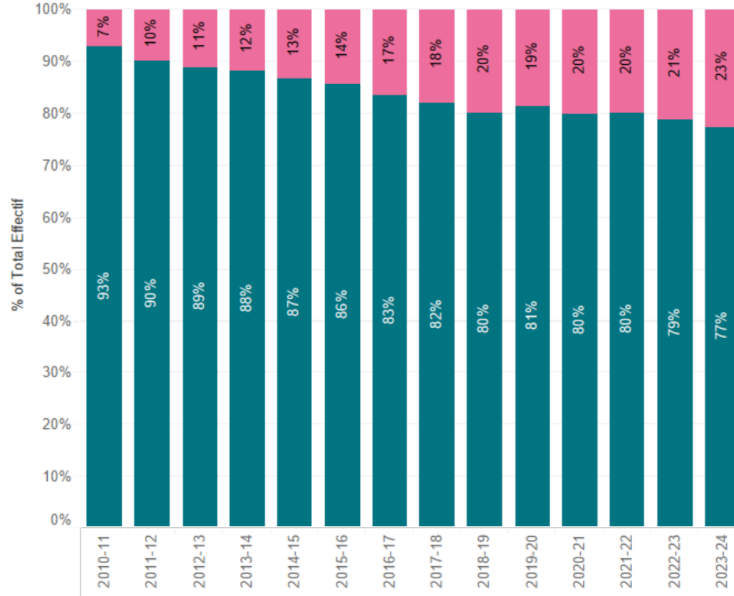


Master Microengineering & Robotics

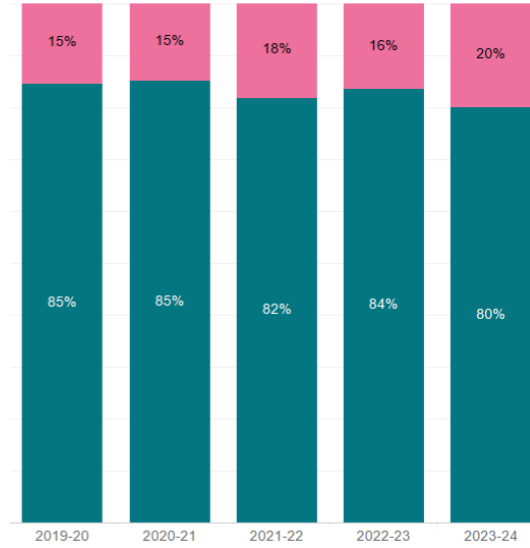


Gender balance

Bachelor



Robotics Master

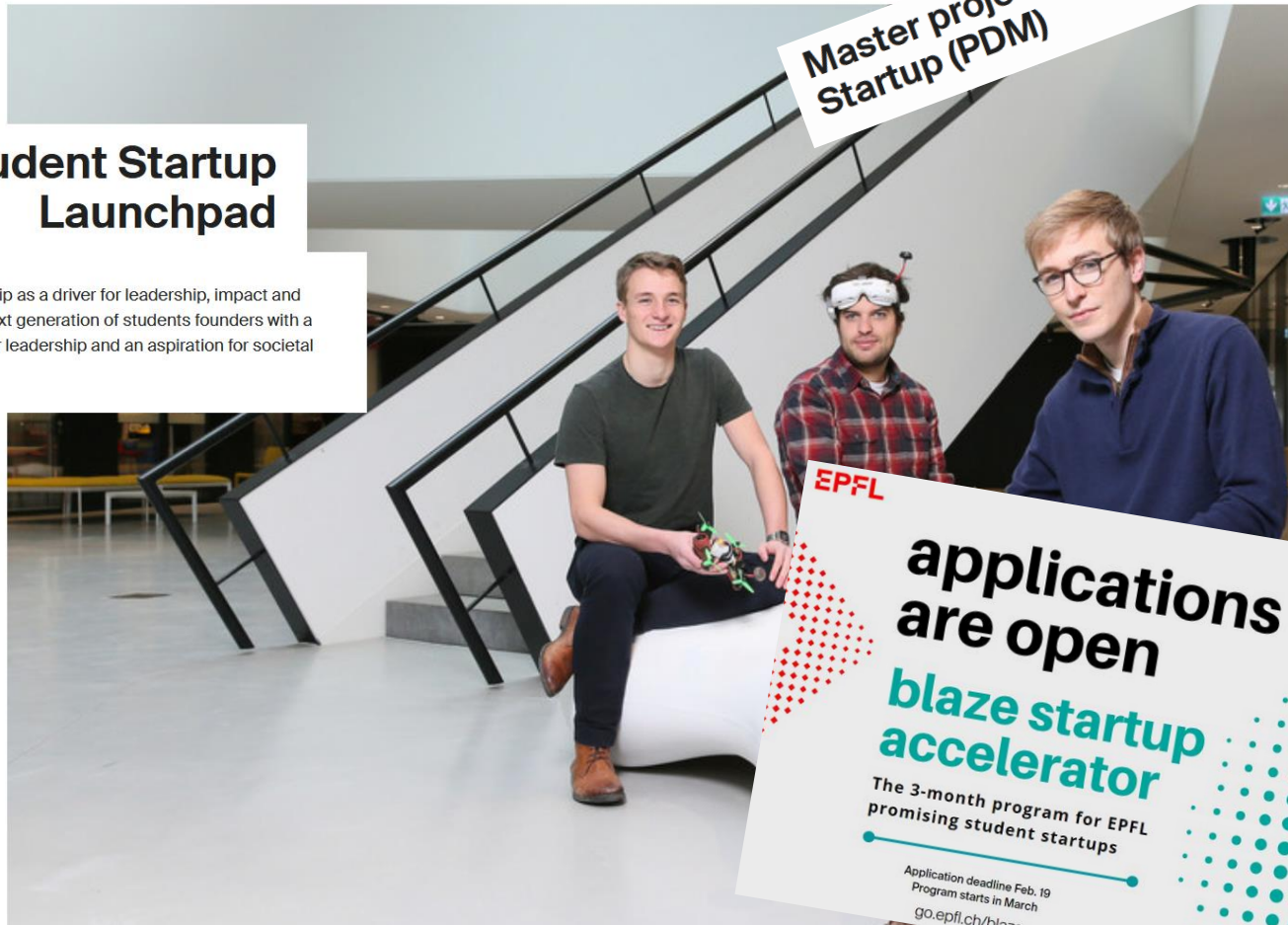


Entrepreneurship !

Student Startup Launchpad

We foster student entrepreneurship as a driver for leadership, impact and innovation. We are building the next generation of students founders with a drive for excellence, an instinct for leadership and an aspiration for societal impact.

Master project in your
Startup (PDM)



EPFL

applications
are open

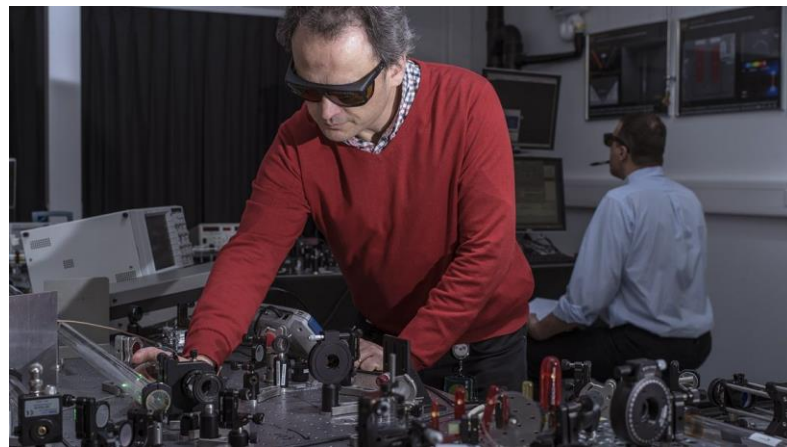
blaze startup
accelerator

The 3-month program for EPFL
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Application deadline Feb. 19
Program starts in March

go.epfl.ch/blaze

Research - IEM to host your projects



IEM covers the following major technical fields:

- Electronic Circuits and Devices
- Micro-manufacturing and Micro- and Nano-technologies
- Robotics
- IoT, Computer & Communication Engineering
- Optics, Photonics and wave engineering
- Machine learning, Information Science and Systems
- Power and Energy

Research in IEM :

- 37 Full Professors / Associate Professors / Tenure-Track Assistant Professors
- 1 SNSF-funded Professor
- 13 Adjunct Professors
- 11 Senior Scientists
- 1 Member of the US National Academy of Engineering
- 1 Member of the American Academy of Arts & Sciences
- 1 Member of the Academia Europaea
- 2 Members of Swiss Academy of Engineering Sciences
- 25 ERC grants : 12 Advanced, 6 Consolidator and 7 Starting grants since 2008

One Institute on 3 campuses

EPFL
iem
institute of **electrical**
and **micro** engineering

Geneva - Campus Biotech

- Bio- and neuroengineering (Wyss center)
- Human Brain Project
- Center for neuroprosthetics

• 420 staff
• 9 chairs
• 3880 m²

Neuchâtel - Microcity

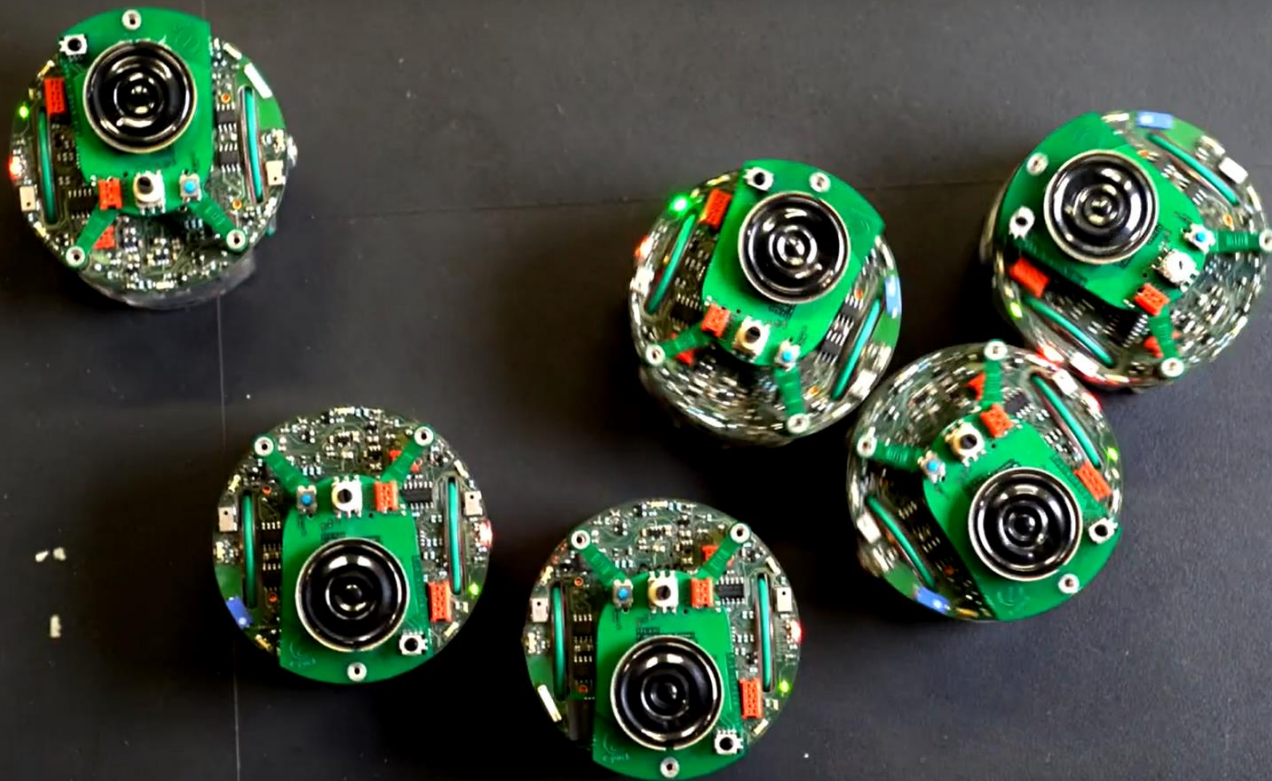
- Microengineering and nanotechnologies

• 230 staff
• 11 chairs
• 8035 m²



Short Movie to learn more

Robotics at EPFL



Student Testimony



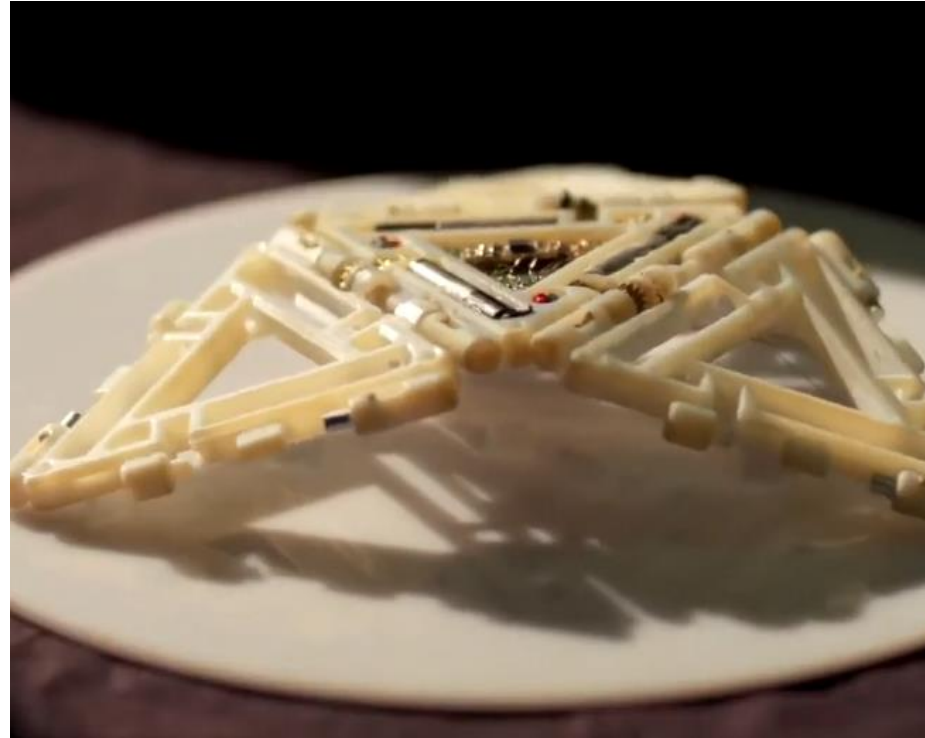
Sébastien de Rivaz
about the Robotics Master



Student Testimony



Arwen Blanche Giraud
about the Robotics Master



Alumni Testimonies



Adrien Briod
Founder and CTO
Master Microtechnique terminé en 2009
Thès doctorat EPFL 2013



We wish you a successful continuation of your Bachelor studies and hope that you will make the right choice for your Master !

